Robotic Surgery for Giant Presacral Dumbbell-Shape Schwannoma

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Abstract

Objective: To demonstrate the feasibility of using da Vinci robotic surgical system to perform spinal surgery.

Methods: Magnetic resonance imaging (MRI) of a 29-year-old female patient complaining right pelvic pain for 1 month revealed a 17x8x10 cm non-homogeneous dumbbell shape encapsulated mass with cystic change located in the pelvic cavity and caused an anterior displacement of urinary bladder and colon.

Results: There was no systemic complication and pain decrease 24 hours after surgery and during 2 years of follow up. The patient started a diet 6 hours after the surgery and was discharged 72 hours after the surgery. The pathological diagnosis of the tumor was schwannoma.

Conclusions: Giant dumbbell shape presacral schwannomas are rare tumours and their surgical treatment is challenging because of the complex anatomy of the presacral. Clinical application of da Vinci robotic surgical system in the spinal surgical field is currently confined to the treatment of some specific diseases or procedures. However, robotic surgery is expected to play a practical future role as it is minimally invasive. The advent of robotic technology will prove to be a boon to the neurosurgeon.

Keywords: da Vinci robotic surgical system, presacral, schwannoma

Introduction

Schwannoma, that is mostly benign peripheral nerve sheath tumor, arises from the Schwann cells. It grows slowly and asymptomatically in approximately 1 of 40,000 patients admitted in hospitals, most commonly in the age group of 40- and 60-years, with a male to female ratio of 2:3.1,2 The predilection areas include the head and neck; extremities and posterior mediastinum; and retroperitoneum or pelvis. The presacral space, in particular, is a peculiar anatomic area between the posterior wall of the rectum and the anterior surface of the sacrum, extending upwards to the peritoneal reflection and downwards to the rectosacral fascia (Waldeyer). The lateral boundaries are the endopelvic fascia (lateral ligaments), the ureters and the iliac vessels.3,4 Schwannoma occurring in this area is known as the presacral schwannoma. There are three types of giant presacral schwannoma based on anatomical findings; the retroperitoneal schwannoma, the intraosseous (intraspinal) schwannoma, and the spinal (dumb-bell) schwannoma.5,6,8

During the past decade, robotic surgical systems have continuously been developed. These advances have allowed the substitution of laparoscopic procedures in many surgical fields owing to its 3D vision and enhanced ergonomics. The 6 degrees of freedom, that is provided by the robot instrumentation, in combination with a 3D high-definition image and rock steady operating arms allow neurosurgeons to operate in an extreme view. Furthermore, the magnification offered by the endoscope varies from 12x to 40x depending...
on its proximity to the target tissue. As of the present, the application of this technology for the excision of a presacral tumor has appeared in the literature in only one report. Although robotic surgery is presently an interesting and emerging technique in various surgical fields, the effectiveness of this equipment is still under debate. The goal of this article is to review the da Vinci surgical system, which is the currently most well known robotic surgical system.

**Case**

A 29-year-old female patient complained of a right pelvic pain for 1 month. Pelvic magnetic resonance imaging revealed the presence of a 17x8x10 cm non-homogeneous encapsulated mass with cystic change located in the pelvic cavity. This tumor had caused an anterior displacement of the urinary bladder and colon (Fig. 1).

The tumor was removed for biopsy through an open posterior laminectomy of the sacrum in prone position and, a week later, da Vinci robot procedure via transperitoneal approach in a supine position was performed. Once the patient was placed in a supine position, the da Vinci robot was docked and a neurosurgeon then sat by the robotic console while assistance was provided by a digestive surgeon at the side of the operating table. A 12 mm trocar for the camera was inserted just above the umbilicus. Two 8-mm trocars were introduced 8–10 cm away from the camera port (Fig. 2). A trocar for the right side of robotic arm was introduced and was directed to the symphysis pubis while the left side trocar was at an intersection point between the left mid-clavicular line and the imaginary line from umbilicus to left anterior superior iliac spine. Another 12-mm trocar was made for suctioning and assisting between the camera port and 8-mm trocar. The distances between the trocars were wide enough to avoid collisions of instruments (Fig. 3B). After the trocar insertion, the da Vinci Surgical System® was introduced from the backside of the patient cart. Maryland bipolar forceps and monopolar curved scissors were employed as the left and right instruments, respectively (Fig. 3C). Detachment of the large bowel from the posterior peritoneal wall was performed. Incision of the posterior peritoneum was made and small vessels traversing the tumor capsule were coagulated with bipolar forceps.

![Fig. 1 a) Destruction of Os Sacrum (asterisk) b) Axial Image of NC CT-Scan Large Encapsulated and Bone Defect in Sacral Area c) Coronal Images of T2-weighted MRI Showed Foraminal Enlargement of the Sacrum d) Non-homogenous Hyperintense Presacral Mass on T2-weighted MR Image.](image-url)
and incised with an activated scissors. The tumor capsule was extremely thin and friable; however, the tumor was not soft enough to be removed with suction. Considering that condition, an intracapsular tumor debulking was undertaken; tumor was resected following a circumferential dissection and excised with minimal traction on the originating nerve (Fig. 3D). A subtotal excision left a part of the capsule to preserve the nerve. The specimen was placed in the EndoCatch retrieval bag (Autosuture, Norwalk, CT, USA) and removed through the assistant port. Amount of bleeding was less than 100 cc. Setup time for the da Vinci Surgical System® was 40 min, and the total time of anesthesia was 180 min. The sum of all incision sizes was 8 cm. Although bleeding was minimal, an indwelling catheter was left attached for the possibility of any delayed bleeding. The catheter was withdrawn the day after the surgery. The patient started consuming meal 6 hours following surgery and was discharged 72 hours after the surgery. Histopathologically, the tumor was composed of spindle cells growing in fascicles in a fibrillar background and consisted of verocay bodies characteristic for antoni type A schwannoma (H&E 200x) although less cellular, which is characteristic of an antoni type B (Fig. 5). There were no systemic complication and pain remain decreased during 2 year follow up.

Fig. 2 Artist Diagram Shows Port Placement for Robot-assisted Presacral Tumor Resection

Table 1 Advantages and Disadvantages of Robotic Assisted Surgery

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<tr>
<th>Advantage</th>
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<td>Excellent visualization</td>
<td>Absence of tactile sensation</td>
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<tr>
<td>Improve dexterity</td>
<td>High cost</td>
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<td>Motion scaling</td>
<td>Unproven clinical benefit</td>
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<td>Tremor elimination</td>
<td>Demand learning curve</td>
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<td>Elimination of fulcrum effect</td>
<td>Less flexible than human</td>
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<td>Tele manipulation</td>
<td>Hand eye coordination</td>
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<tr>
<td>Ergonomic position</td>
<td>Less infection (unproven)</td>
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<td>Less radiation exposure</td>
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Discussion

Presacral schwannomas are presumed to be arisen from a peripheral nerve in or adjacent to an anterior sacral foramen. Therefore, they are able to grow outside of the boundaries of the bone with limited degree of secondary bone.
Fig. 3 Operative Findings of Robot-assisted Presacral Tumor Resection. (a) da Vinci Robot was then Docked, Neurosurgeon then Sat by the Robotic Console, (b) Collaboration with Digestive Surgeon, (c) Dissection of Tumor through Robotic Bipolar Forceps and Monopolar scissors, DL, Left Arm of da Vinci; DR, Right Arm of da Vinci; F, paracolic fat. (c) Tumor was Removed Successfully with Robot Assisted

Fig. 4 da Vinci Surgical Robot System

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involvement with presacral retroperitoneum as the potential space. These are the possible reasons why these slowly growing tumors can develop to such a large size prior to any clinical symptoms. A presacral schwannoma is uncommon and usually asymptomatic when it is small. Retrorectal masses are typically slow growing that very mild pain in the perineal area is the most common symptom reported by patients during malignant or inflammatory processes. The tumor is often discovered after producing pain and showing neurological symptoms.\textsuperscript{14–16} Although it is rare, presacral lesions can include various types with almost 50% of presacral tumors are malignant or have areas of malignant changes within them with solid tumors having a higher probability of malignancy than the cystic lesions (60% vs 10%).\textsuperscript{5,17}

Magnetic resonance imaging (MRI) technique is helpful in detecting specific characteristic and specific radiological features associated with schwannomas. The following findings are highly suggestive: a well-demarcated round or oval mass with non-homogeneous contrast enhancement due to cystic and haemorrhagic changes, presence in the region of a known nerve ganglion or pathway; calcification and cystic change in a large tumour, iso- or slightly hyperintense signal intensity on T1 weighted images compared to muscle, and a high signal intensity on T2 weighted images.\textsuperscript{4,18} Heterogeneity can be seen on MRI imaging, which reflects degenerative change of long-standing schwannomas. There is the so-called "ancient schwannoma" referring to a degenerative schwannoma typified by cyst formation, hemorrhage, calcification, and also fibrosis. Magnetic resonance imaging can also differentiate malignant schwannomas from benign ones by identifying indistinct margins or a lack of a pseudocapsule.\textsuperscript{18}

Robotic surgery has become popular for gynaecologic or urologic tumors, in spinal surgery, however, tumor outside the vertebral column such as paravertebral or presacral tumor are some of the relevant indications. Even though this operation was performed in cooperation with a laparoscopic digestive surgeon, an experienced neurosurgeon who is accustomed with the basic principles of port placement robot assisted approach shall not require a steep learning curve.\textsuperscript{10} The method still has many limitations, thus requires human assistance (Table 1). The combination of pure laparoscopic approach and the latest robotic technology enabled us to complete the first successful robotic removal of a spinal tumor with minimal morbidity, a brief hospital stay, and rapid postoperative recovery.

It can be concluded that giant presacral schwannomas are rare tumours and their surgical treatment is challenging due to the complex anatomy of the presacral. Clinical application of robotic surgery in the spinal surgical field is currently confined to some specific disease treatments or procedures. It is therefore expected that robotic surgery will play a practical future role as a minimally invasive procedure. We believe that the advent of robotic technology will prove to be a boon to the neurosurgeon.

Fig. 5 a) Macroscopic Tumor Following Peacemeal Resection b) Tumor Composed of Spindle Cells Growing in Fascicles in a Fibrillar Background and Consist of Verocay Bodies and was Hypercellular Characteristic for Antoni Type A Schwannoma (H&E 200X). c) Hypocellularity, Characteristic for Antoni Type B.\textsuperscript{4,5}
References